Spontaneous pattern formation in driven nonlinear lattices

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(Received 16 April 2000)

We demonstrate the spontaneous formation of spatial patterns in a damped, ac-driven cubic Klein-Gordon lattice. These patterns are composed of arrays of intrinsic localized modes characteristic for nonlinear lattices. We analyze the modulation instability leading to this spontaneous pattern formation. Our calculation of the modulational instability is applicable in one- and two-dimensional lattices; however, in the analyses of the emerging patterns we concentrate particularly on the two-dimensional case.

PACS number(s): 63.20.Ry, 45.70.Qj, 63.20.Pw

Complex spatial patterns are often observed in systems driven away from equilibrium [1]. Typically, the patterns emerge when relatively simple systems are driven into unstable states that will deform dramatically in response to small perturbations. As the patterns are arising from an instability, the pattern-forming behavior is likely to be extremely sensitive to small changes in system parameters. The description of deterministic pattern-forming systems has typically been accomplished in the form of partial differential equations such as the Navier-Stokes equations for fluids and reaction-diffusion equations for chemical systems. These phenomena have primarily been studied in continuum systems such as hydrodynamical, optical, and chemical systems and liquid crystals, although more recently pattern formation of a similar type has also been reported in periodically vibrated granular media [2].

Complementing the development of the theoretical understanding of pattern formation in continuum systems, the localized mode forming ability of *discrete* lattices has also received significant recent attention. There is now a fairly complete understanding of the existence and stability of localized structures [often referred to as intrinsic localized modes (ILM's) or discrete breathers] in a variety of nonlinear lattices, undriven [3] as well as driven [4]. It is fair to claim that these collective patterns are well understood while the process of their creation and interaction remains relatively unexplored.

In the present paper we study the pattern-forming abilities of a damped and periodically driven nonlinear lattice. Specifically, we demonstrate how a driven nonlinear (cubic) Klein-Gordon lattice forms a variety of patterns via modulational instabilities. We analyze the modulational instabilities and show how these relate to the length scale of the patterns that are formed. Normally, the spatial extent (characteristic length scale) of ILM's is directly related to the frequency of the ILM's [3]. However, in our case the (generally different) length scale emerging from the instability may lead to a length-scale competition, the results of which we will explore.

Model and stability of the homogeneous solution. First, we study the Klein-Gordon lattice

$$\ddot{x}_n + \gamma \dot{x}_n + \omega_0^2 x_n = \Delta_n x_n + \lambda x_n^3 + \epsilon \cos \omega t, \qquad (1)$$

where γ is the damping parameter, ω_0 the natural frequency of the oscillators, $\lambda = \pm 1$ the nonlinearity parameter, and ϵ the amplitude of the ac drive at frequency ω . In one dimension the nearest neighbor coupling is $\Delta_n x_n = x_{n+1} - 2x_n$ $+ x_{n-1}$ [5]. The amplitude A_0 (and phase δ_0) of the spatially homogeneous solution $x_n = A_0 \cos(\omega t + \delta_0)$ of Eq. (1) can be shown to satisfy, within the rotating wave approximation,

$$A_0^2 \left[\gamma^2 \omega^2 + \left(\omega^2 - \omega_0^2 + \frac{3}{4} \lambda A_0^2 \right)^2 \right] = \epsilon^2.$$
 (2)

The amplitude A_0 of the response to a driving amplitude ϵ is shown for the *soft* ($\lambda = 1$) potential in Fig. 1. For $\omega < \omega_0$ (dashed line) three solutions are possible, while for $\omega > \omega_0$ (solid line) a single solution is possible. A similar picture is valid for the *hard* ($\lambda = -1$) potential except that the multiple solutions then appear in the case $\omega > \omega_0$.



FIG. 1. Amplitude A_0 of response vs driving amplitude ϵ of the ac drive at frequency $\omega = 1.2\omega_0$ (solid line) and $\omega = 0.8\omega_0$ (dashed line). Remaining parameters are $\omega_0 = 1.3$, $\gamma = 0.15\omega_0$, and $\lambda = 1$ (soft potential).

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FIG. 2. Instability region (shaded) in the (ϵ, k) plane. Dashed line indicates the most unstable wave number a=1. Parameters corresponds to the solid line in Fig. 1.

Analyzing the stability of the homogeneous solution with respect to spatial perturbations, we introduce $x_n = y + z_n$ into Eq. (1). Assuming periodic boundary conditions, we may expand z_n in its Fourier components $z_n = \sum_k \exp(ikn)\xi_k(t)$, where the mode amplitude $\xi_k(t)$ is then governed by

$$\ddot{\xi}_{k} + \gamma \dot{\xi}_{k} + \omega_{k}^{2} \xi_{k} = \frac{3}{2} \lambda A_{0}^{2} [1 + \cos(2\omega t + 2\delta_{0})] \xi_{k}$$
(3)

with $\omega_k^2 = \omega_0^2 + 4 \sin^2(k/2)$ denoting the linear dispersion relation of the system.

Finally, the transformation $\xi_k(t) = \zeta_k(\omega t + \delta_0) \exp[-(\gamma/2)(\omega t + \delta)] \equiv \zeta_k(\tau) \exp[-(\gamma/2)\tau]$ reduces Eq. (3) to a standard Mathieu equation,



where

$$a = \frac{1}{4\omega^2} (4\omega_k^2 - 6\lambda A_0^2 - \gamma^2) \quad \text{and} \quad q = \frac{3\lambda A_0^2}{4\omega^2}.$$
 (5)

As is well known [6] the Mathieu equations exhibit parametric resonances when $\sqrt{a} \approx i$, where i = 1,2,3,... The width of the resonance regions depends on the ratio q/a (see, e.g., [7]). In the framework of Eq. (4) the extent of the primary resonance $a \approx 1$ can easily [7] be estimated to be $(a-1)^2 < q^2$. However, in the presence of the damping γ the resonance condition for Eq. (3) becomes

$$q^2 > \frac{\gamma^2}{\omega^2} + (a-1)^2,$$
 (6)

with *a* and *q* defined in Eqs. (5). Given λ , γ , ω , ω_0 , and ϵ , this translates into an instability band of certain wave numbers *k*.

Figure 2 shows this instability band as given by Eq. (6) for parameters corresponding to the solid curve in Fig. 1. The shaded region is the band of wave numbers that are unstable according to Eq. (6) and the dashed line indicates the most unstable wave number, i.e., a=1. The effect of the damping clearly is to pinch off the instability region at a finite driving $\epsilon > 0$. Similarly, using Eq. (6) instability regions can be determined for the solutions indicated by the dashed curve in Fig. 1.

We have verified the presence and location of the instability band by direct simulations of Eq. (1) starting from the initial condition $x_n(t=0) = A_0 \cos(\delta_0) + \eta_n$, where η_n repre-



FIG. 3. Stability diagram showing the stability boundaries between the possible patterns in the (ϵ, ω) plane. Parameters are $\omega_0 = 0.75$, $\lambda = -1$ (hard potential), $\gamma = 0.05\omega_0$. The four points refer to the specific spatial structures shown in Fig. 4.



FIG. 4. (Color) Spatial patterns corresponding to the four points marked in Fig. 3 for $\epsilon = 0.57$: (a) straight stripes ($\omega = 0.8\omega_0$), (b) modulated stripes ($\omega = 0.88\omega_0$), (c) rhombi ($\omega = 1.0\omega_0$), (d) localized rhombi ($\omega = 1.2\omega_0$). $x_{n,m}$ is plotted along the vertical axes.

sents a small $(|\eta_n| \ll A_0)$ spatially random perturbation. This initial condition injects energy into all wave numbers and in the presence of an unstable region of wave numbers the dynamics will enhance the energy content in this region and thereby identify the unstable region.

The above analysis is easily extended to the case of two spatial dimensions [5], the only required change being that the dispersion relation now is $\omega_k^2 = \omega_0^2 + 4 \sin^2(k_x/2) + 4 \sin^2(k_y/2)$, where the wave vector is $\vec{k} = (k_x, k_y)$. The instability in this case appears on an annulus in the wave vector plane, with a radius given by a = 1 [see Eq. (5)] and a width determined by Eq. (6).

Pattern formation. Numerical simulations allow us to not only verify the predicted instability band, but also to follow the full nonlinear development and saturation initiated by the instability. In particular, in regions of parameter space we obtain the spontaneous formation of patterns of distinct spatial geometry. Although we have observed this behavior in one as well as in two dimensions, in the present paper we focus on the two-dimensional system, where the pattern formation is very rich.

Although the dynamics show different features according to the specific region of parameter space, it is possible to trace a typical behavior as follows. Initializing the system in the spatially homogeneous state described above with a small amount of randomness added, the instability sets in after a certain number of cycles of the ac drive, depending on the strength of the parametric resonance, i.e., on the value of $\sqrt{a} \approx 1,2,3,\ldots$. Thereafter the system usually evolves through a sequence of different patterns (rhombi, stripes, etc.), composed of localized regions of high amplitude oscillations, before reaching a final configuration that may or may not result in a structure of definite symmetry.

Due to the sensitive response to very small changes of the parameters, determining stability regions for the different pattern geometries is a difficult task. However, in the case of a hard potential ($\lambda = -1$), Fig. 3 shows a limited area of (ϵ, ω) space in which distinct spatial patterns emerge and remain stable.

This diagram is constructed by following the full dynamics of the system for thousands of cycles. As our study concentrates on patterns arising from instabilities of the homogeneous solutions, we do not discuss possible hysteretic behavior such as is sometimes observed in similar systems (see, e.g., Ref. [2]).

Figure 4 shows representative examples of the spontaneously emerging patterns corresponding to the points marked in Fig. 3. The patterns consist of localized regions of high amplitude coherent oscillations (ILM's) residing on a background that oscillates at the frequency ω of the ac drive. In all the considered cases we have observed the natural result that patterns are energetically sustained only when the ILM, ω_{ILM} , and driving, ω , frequencies are commensurate, i.e., $\omega_{ILM} = n\omega$, where *n* is an integer. For the patterns displayed in Fig. 4, *n*=2. Further, the motion of the ILM's is out of phase, i.e., at the points in time where the background oscillation reaches its maximal excursion the ILM's obtain their minimal amplitude, such that at these points the state is completely homogeneous.



FIG. 5. (Color) Snapshot of spontaneously formed pattern of ILM's. The red line represents a one-dimensional cut of the pattern array, whose dynamics we have analyzed in detail (see Fig. 6).

At a fixed driving ϵ , for increasing values of the frequency ω , as in Fig. 4, we can observe the following behavior. Due to the presence of the damping γ , at sufficiently small ω the spatially homogeneous solution is stable against all possible spatial modulations such that the *flat* state is sustained. However, for values near point (a) the system becomes unstable with respect to certain spatial modulations and spatial patterns in the form of large stripes emerge [Fig. 4(a)]. On increasing the frequency, these stripes become thinner and denser and begin to show an increasingly clearer modulation [Fig. 4(b)]. The characteristic length scale of these patterns is set by the size of the unstable k vector according to the above analysis. The nonlinear character of the system results in a transition toward a more isotropic geometry (rhombic) as the driving frequency is increased further [Fig. 4(c)]. As in the case of the stripes, stronger localization of the ILM's arranged in the rhombic pattern [Fig. 4(d)] is observed for even larger driving frequencies. The angle between the sides of the rhombus unit cell varies but for the hard potential it is always close to $\pi/2$. For values of ϵ larger than those displayed in Fig. 3, the final mesoscopic patterns of the system dynamics are spatially disordered much like the phenomena observed in granular media [2]. It is important to realize that the length of the unstable wave vector determines the length scales of the final patterns, while the symmetry of the patterns is determined by the nonlinear character of the system.

As a result of the periodic boundary conditions, the length scale of the emerging patterns must be commensurate with the system size. However, we have observed that the existence of a band (variable in length and angle) of unstable \vec{k}

vectors (see Fig. 2 and related discussion) allows continuous accommodation of this constraint except for the discontinuous changes in length scales occurring when it is energetically favorable for the system to add (or subtract) an additional stripe (or row of ILM's).

For the soft potential $(\lambda = 1)$ variation of the amplitude ϵ and the frequency ω of the ac drive is particularly problematic, as the dynamics in this case can lead to the development of catastrophic instabilities as one or several oscillators overcome the finite barrier in the quartic potential. In all the cases we have been able to simulate, the early stage time evolution of the system is characterized by the formation of ILM's



FIG. 6. ILM dynamics monitored along the direction indicated by the line in Fig. 5.

regularly arranged in a square pattern. This spatial configuration, which is sustained for up to hundreds of cycles, seems always to suffer from a weak instability and eventually deforms into a rhombic pattern, as shown in Fig. 5. Contrasting with the case of the hard potential (λ =1), here in the soft potential the angle between the sides of the rhombus unit cell is always close to $2\pi/3$ (so almost hexagonal).

We now analyze this pattern more closely. The pattern shown in Fig. 5 consists of ILM's spontaneously organized into a regular rhombic pattern. The ILM's are spatially localized and perform harmonic temporal oscillations (at the frequency ω of the ac drive) and are therefore objects that are, in isolation, well described [3] in the literature. A particular feature of these ILM's is that they reside on a background that oscillates at the same frequency. To expose the dynamics of the ILM's more closely, we show in Fig. 6 a time sequence along a one-dimensional cut of the twodimensional system (the cut is indicated by the line in Fig. 5). It should be noted that in Fig. 6 we have removed the oscillations of the background in order to clearly expose the ILM dynamics.

Although we have focused on the ILM dynamics in the case of a soft potential, the features are analogous in the case of the hard potential and only the symmetry of the patterns is different.

In summary, we have studied the modulational instability in a damped and ac-driven cubic nonlinear Klein-Gordon lattice. The analysis applies to one as well as two spatial dimensions. We have further demonstrated numerically how these instabilities lead to a variety of mesoscopic patterns of intrinsic local modes. In the case of a hard potential we characterized the patterns in a stability diagram, and in the case of a soft potential we showed that the dynamics always result in a rhombic pattern with an angle close to $2\pi/3$. These rhombic patterns were never observed in the case of the hard potential. This difference in the shapes of the patterns in the hard and soft cases can be understood by exploiting the analogy between the changes in the steady states of a dissipative systems and phase transitions in systems at thermodynamic equilibrium (see, e.g., Ref. [8]). In terms of this analogy, the appearance of spatially periodic structures in a nonequilibrium system can be connected to a perturbation of the translational symmetry of thermodynamic states in equilibrium. A study based on this philosophy was pursued in Ref. [8] with the result that the angle defining the rhombic patterns is given by the coefficient of the cubic term in the system, which is indeed our observation here. From the present analysis it appears that experimental studies of the patternforming abilities of discrete systems present an excellent opportunity to study ILM's and their mutual interactions and mesoscopic patterning. For example, optical systems [9] and spin systems [10] appear good candidates for such studies.

Research at Los Alamos National Laboratory was performed under the auspices of the U.S. Department of Energy.

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